Parametric 3D inversion of airborne time domain electromagnetics

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SUMMARY

Conventional voxel-based inversion algorithms can encounter difficulties when inverting airborne time-domain electromagnetic data in three dimensions. In certain environments with these codes, it can be challenging to delineate sharp boundaries between geologic units with large conductivity contrasts and to accurately image thin conductive targets. Furthermore, spurious circular inversion artifacts, known as ringing, can occur around conductive targets.

To address these issues we have developed a parametric inversion code that can be used to find the optimal location, shape and conductivity value of a single anomaly in a homogeneous or heterogeneous background. The algorithm incorporates a Gauss-Newton optimization scheme in conjunction with a level set formulation to outline the anomaly of interest, and can be combined with a conventional voxel-based algorithm in more complicated geologic settings.

The code is shown to be successful with a synthetic data set over a thin dipping plate, and two field data sets. For the synthetic scenario, the parametric inversion recovers the true dip and size of a conductive target with no a priori information. The algorithm also accurately defines the extent of a diamondiferous kimberlite pipe and a dipping massive sulphide deposit beneath a conductive overburden.

Key words: parametric, inversion, electromagnetics, level sets.

INTRODUCTION

Airborne electromagnetic (AEM) surveys are an important part of many mineral exploration programs, especially when attempting to image buried conductors. When performing three-dimensional (3D) inversions on AEM data sets, conventional voxel-based inversions such as Oldenburg et al. (2013) can have difficulty in resolving thin targets or sharp boundaries between two contrasting resistivity units. With a typical least-squares regularization, this results in a smeared anomaly or border, which can pose problems during interpretation or drill targeting. Another issue is the circular nature of the sensitivity from a coincident loop airborne system, which can cause inversion artifacts known as ringing. This can result in conductive features to be erroneously placed around the true conductive target in a ring-like manner.

Parametric inversions are well researched methods of reducing the parameter space of an inverse problem (Dorn et al., 2000; Zhdanov and Cox, 2013), and can alleviate some of the issues conventional inversions face. Parametric inversions can also be coupled with such methods as level sets (Osher and Sethian, 1988), and together they can solve for the boundary of a conductivity anomaly (Dorn et al., 2000; Aghasi et al., 2011). This enables a computationally efficient method of imaging compact anomalies and sharp boundaries with greater ease without the issue of ringing. Consequently, we incorporate a parametric inversion with level sets for time domain airborne electromagnetics, and demonstrate its applicability to both synthetic and field data sets.

METHODS

Our parametric approach searches for one anomaly of interest, either conductive or resistive, in a background of arbitrary conductivity. This background can either be a uniform half-space or a heterogeneous conductivity from a priori information or another inversion algorithm. The conductivity of the anomalous body can be fixed by the user, or the optimal conductivity can be a parameter in the inversion. In the case of a uniform background, the best-fitting background conductivity can also be found. The inversion solves time-dependent quasi-static Maxwell’s equations

\[ \nabla \times \mathbf{E} + \mu \mathbf{H} = 0 \quad (1) \]
\[ \nabla \times \mathbf{H} - \sigma \mathbf{E} = \mathbf{s} \quad (2) \]

with a finite volume discretization where \( \mathbf{E} \) and \( \mathbf{H} \) are the electric and magnetic fields, subscript \( t \) is the time derivative, \( \mu \) is the magnetic permeability, \( \sigma \) is the electrical conductivity and \( \mathbf{s} \) is a source term. The anomalous conductivity body has the shape of a skewed Gaussian ellipsoid, which is defined by first calculating a smoothly varying function \( \tau \)

\[ \tau = c - (x - x_0)^T \mathbf{M} (x - x_0) \quad (3) \]
where \( c \) represents a positive constant, \( \mathbf{x} \) is a vector of observation points in three dimensions, \( \mathbf{x}_0 \) is vector with spatial coordinates of the anomaly centre, and \( \mathbf{M} \) is a \( 3 \times 3 \) symmetric, positive definite matrix with skewing and rotation parameters. The function \( \tau \) is passed to an analytic step-off function \( s \)

\[
s(\tau) = \sigma_0 + 0.5(1 + \tanh(\alpha \tau))(\sigma_1 - \sigma_0) \tag{4}
\]

that assigns the conductivity to either a background \( \sigma_0 \) or anomalous \( \sigma_1 \) level. When \( \tau = 0 \), also known as the zero level set, a transition zone occurs between \( \sigma_0 \) and \( \sigma_1 \) with a width controlled by the parameter \( \alpha \). The optimization of the inversion follows a Gauss-Newton procedure, where the sensitivity is composed of derivatives of the function \( s \) with respect to the inversion parameters. This optimization scheme is like many conventional voxel-based codes (Oldenburg et al., 2013), but the regularization has been removed because our initial tests have empirically found it is not required. The inversion parameters however, are scaled to ensure a well-conditioned Gauss-Newton matrix, and a line search determines an appropriate step length. The program terminates once it has either reached a desired level of convergence, a maximum number of iterations, or when a suitable Gauss-Newton step cannot longer be found. If desired, the parametric result can be set as the initial model for a conventional inversion to resolve additional features of interest. This process can be iterated to optimize both the anomalous body and surrounding background features.

RESULTS

Three examples will be discussed that showcase the versatility of this parametric code. The first is a synthetic model of a thin conductive dipping plate of 3 ohm-m in a background of 3000 ohm-m as shown in Figure 1a. The synthetic data are generated by simulating a coincident loop airborne EM survey with seven east-west lines with a line spacing and data spacing of 100 m. There are a total of 49 transmitter locations, each 37.5 m above topography. The data consists of 19 time channels between 10 \( \mu \)s and 7000 \( \mu \)s. Five percent Gaussian noise is added to the data prior to inversion. The initial starting guess consists of a 50 m radius sphere of 3 ohm-m centred over the anomaly at an elevation of 200 m below surface. The guess is designed to provide little in the way of a priori depth information and no dip information. The conductivity of the plate and background are kept fixed throughout the inversion.

The second example comes from the Tli Kwi Cho (TKC), DO-27, diamondiferous kimberlite in the North-West Territories, Canada. A cross section through the kimberlite pipe, located in the Slave craton, is shown in Figure 4. This displays a mostly vertical pipe that widens as it approaches the surface (Harder et al., 2008). In this setting, the conductivity of the background rock, which is primarily granite, is quite resistive, whereas the pyroclastic kimberlite itself possesses a more conductive signature, due to extreme alteration and the presence of serpentine (Eggleston et al., 2014). This results in a noticeable

![Figure 1: a) Synthetic true model. Plate parameters: 3 ohm-m, 60m thick, 320m in strike length, depth extent ranges from 200m to 800m below surface. Background = 3000 ohm-m b) Parametric recovery.](image)

![Figure 2: a) Observed data at 1.11e-3 seconds b) Predicted data at 1.11e-3 seconds. The predicted data closely matches the observed data. Transmitter points shown as black dots.](image)

![Figure 3: Synthetic inversion result at a depth of 400m using a conventional voxel-based inversion. The true outline of the dipping plate is shown in solid white. Ring-like structures occur around the true anomaly.](image)
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and distinct AEM anomaly, which is ideal for our parametric inversion.

In 2004, a Versatile Time Domain Electromagnetic (VTEM) survey measured z-component dB/dt data over the TKC kimberlite. Six east-west lines, with a line spacing of 75 m were inverted with the parametric code. The inversion includes a total of 194 transmitter locations, each with ten time channels between 90 \( \mu \)s and 350 \( \mu \)s. Later time channels exist but contain too much noise to be deemed beneficial.

The initial guess for the parametric inversion is a 150 m radius sphere of 1 ohm-m in a 1000 ohm-m background centred over the AEM anomaly. Unlike the synthetic example, the conductivity of the anomaly and background can freely change and Figure 5 portrays a cross-section through the resulting parametric model after 18 Gauss-Newton iterations, along the same Northing as the geologic image from Figure 4. The final conductivity values of the anomaly and background are 27 and 1009 ohm-m respectively.

The resemblance between Figures 4 and 5 is quite similar, as the parametric inversion does an excellent job in capturing the boundaries of the kimberlite, and even the slight dip to the West. Observed and predicted data agree to a satisfactory level.

We approach this issue by first inverting for the mineralized zone with the parametric code, and importing the result into a conventional voxel-based EM inversion code to fill in the background features such as the overburden layer. The process can be iterated multiple times if needed, but for this example we performed a parametric and conventional inversion only once, with 12 Gauss-Newton iterations needed for the parametric code. Due to the more complex geologic setting, we applied a more sophisticated starting model based on a priori information (Prikhodko et al., 2012). This was a near-vertical 100m thick, 0.13 ohm-m thin plate in a 1000 ohm-m background. The final inversion conductivity values are 0.07 ohm-m and 2042 ohm-m respectively.

The final example is from the Caber volcanogenic massive sulphide (VMS) deposit in Quebec, Canada where the target is a thin dipping conductor. In 2012, eight lines of z-component dB/dt AEM data over the deposit were acquired with the VTEM-35 system. Lines were separated by 50m for a total of 102 transmitter locations. Time channels ranged from 505 \( \mu \)s to 2021 \( \mu \)s. A simplified cross-section through the deposit is displayed in Figure 6 (Legault et al., 2010). This image illustrates a steep South-West dipping mineralized area next to a shear zone in amongst a host of resistive intrusive rocks underneath a conductive overburden. The mineralized region, coupled with the adjacent shear zone, represent the conductive target of interest. However, in this setting, the conductive overburden represents another conductive feature to consider.

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Figure 4: Geologic cross section through the DO-27 kimberlite at a Northing of 7133829. Image modified from Harder et al., (2008).

Figure 5: Parametric cross-section through the DO-27 kimberlite at a Northing of 7133829. There is a strong agreement with the geologic cross section in terms of the size and shape of the anomaly.

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A cross section through the resulting model at the centre of the deposit is shown in Figure 7. This image demonstrates the ability to combine the parametric code to image both the target of interest as well as the near-surface overburden layer. The dip of the target matches the geologic cross-section nicely, and a thin overburden exists over the anomaly and thickens to the North-East as does the cross-section in Figure 6. Some differences do occur as the parametric recovery is slightly wider than what the geologic cross-section suggests and extends to a deeper depth.

**CONCLUSIONS**

We developed a parametric algorithm to invert time-domain airborne electromagnetic data and showed that it can be applied to synthetic and field data sets to resolve a number of different targets. The inversion recovers the location and skewing parameters of the anomaly of interest as well as the optimal conductivity value for the target and background if desired. The shape of the anomaly is based on a Gaussian ellipsoid, and the code requires initial guesses for the inversion parameters, after which it follows a Gauss-Newton optimization schedule until a suitable model is found. The result of this parameterization can then be input as the initial model for a conventional voxel-based inversion code to resolve further features of interest.

The parametric inversion proved to be successful in resolving a synthetic buried thin dipping plate, a kimberlite pipe and a buried dipping plate below a conductive overburden. For more complicated target geometries, the parametric code would need to be modified to allow for the recovery of multiple anomalies, and this is the topic of future research.

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