

Supplementary Material

Comparison of ground cover estimates from experiment plots in cotton, sorghum and sugarcane based on images and ortho-mosaics captured by UAV

Tao Duan^{A,B}, Bangyou Zheng^A, Wei Guo^C, Seishi Ninomiya^C, Yan Guo^B and Scott C. Chapman^{A,D,E}

^ACSIRO Agriculture and Food, Queensland Biosciences Precinct, 306 Carmody Road, St Lucia, Qld 4067, Australia.

^BCollege of Resources and Environmental Sciences, China Agricultural University, Beijing, 100 193, China.

^CInstitute for Sustainable Agro-ecosystem Services, The University of Tokyo, Tokyo 188-0002, Japan.

^DQueensland Alliance for Agriculture and Food Innovation, The University of Queensland, St Lucia, Qld 4072, Australia.

^ECorresponding author. Email: scott.chapman@csiro.au

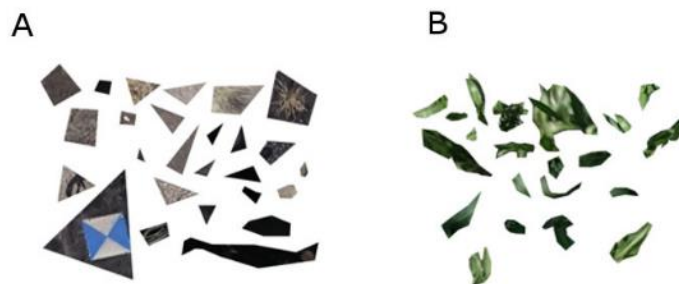


Fig. S1. Acquisition of a training data set from training images. The training data are extracts from undistorted images and ortho-mosaic of the same flight for background (A) and vegetation (B). All pixels that may appear within the planted plot area are considered and other pixels (roads, cars, people, ground control points and so on) are ignored. The example images were taken of sorghum on 12 January 2016, during the early vegetative stage. See Tables 1 and 2 for details.