

**Supplementary material**

**Costs and effectiveness of damage management of an overabundant species (*Sus scrofa*)  
using aerial gunning**

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# Supplemental Information S1: Removal model details with covariates on capture rate.

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This is a standard removal model (Zippin, 1958) accounting for varying in effort (Davis *et al.*, 2016) implemented using data augmentation version (Tanner & Wong, 1987). The data are of the form  $y_{ijk}$ , where  $y_{ijk} = 1$  represents individual ' $k$ ' being removed from site ' $i$ ' during removal pass ' $j$ '. The total number of sites is ' $n$ ', the total number of passes per site is ' $J$ ', and the total number of potential individuals in site ' $i$ ' is ' $m_i$ '. As this is a data augmentation model  $z_{ik}$  is an indicator of an individual being in the population or not, modeled with a Bernoulli distribution with probability  $\psi_i$ . We restricted individuals from being included in the population after they were removed by using an indicator for previous removal.

The removal effort (e.g., hours in the helicopter) for each site ' $i$ ' and pass ' $j$ ' is denoted by  $g_{ij}$ . The site-level removal probability is denoted by  $\theta_i$ , and the removal rate accounting for effort is denoted by  $p_{ij}$ . The capture rate for one unit of effort ( $\theta_i$ ) is modeled with covariates using a logit link. The covariates shown in the model below are *Team* indicating the pilot/gunner personnel team, and *%cover* indicating the amount of canopy cover in the study area  $i$ .

The MCMC algorithm for this model uses a Gibbs sampler with a Metropolis-Hastings step for  $[\theta_i|\bullet]$  (see Gelman et al. 2013 for implementation details). The hyperparameters for  $\alpha_\psi, \beta_\psi, \alpha_\theta, \beta_\theta$  are 1, 2, 1, and 2 respectively. They were chosen to be relatively uninformative. The results were insensitive to the choice of these priors.

## Model

$$y_{ijk} = \begin{cases} 0 & , z_{ik} = 0 \\ \left\{ \begin{array}{l} \text{Bern}(p_{ij}) \\ 0 \end{array} \right. & , \sum_{l < j} y_{ilk} = 0 \\ & , \sum_{l < j} y_{ilk} > 0 & , z_{ik} = 1 \end{cases}$$

$$i = 1, \dots, n \quad (\text{sites})$$

$$j = 1, \dots, J \quad (\text{removal passes})$$

$$k = 1, \dots, m_i \quad (\text{potential individuals at site } i)$$

$$z_{ik} \sim \text{Bern}(\psi_i)$$

$$\Psi_i \sim \text{Beta}(\alpha_\Psi, \beta_\Psi)$$

$$p_{ij} = 1 - (1 - \theta_i)^{g_{ij}}$$

$$\text{logit}(\theta_i) = \mathbf{X} * \underline{\beta}$$

$$\mathbf{X} * \underline{\beta} = \beta_0 + \beta_1 * \text{Team} + \beta_2 * \%cover$$

$$\beta_{0,1,2} \sim N(0, \sigma_\beta^2)$$

## Joint Distribution

$$[\mathbf{z}, \boldsymbol{\psi}, \boldsymbol{\theta} | \mathbf{y}, \mathbf{g}, \mathbf{X}] \propto \prod_{i=1}^n \prod_{j=1}^J \left[ \prod_{k=1}^{m_i} \left( [y_{ijk} | p_{ij}]^{z_{ik}} 1^{(1-z_{ik})} [z_{ik} | \psi_i] \right) [\psi_i | \alpha_\psi, \beta_\psi] [\theta_i | \sigma_\beta] \right]$$

## References

- Davis, A.J., Hooten, M.B., Miller, R.S., Farnsworth, M.L., Lewis, J., Moxcey, M. & Pepin, K.M. (2016) Inferring invasive species abundance using removal data from management actions. *Ecological Applications*, **26**, 2339–2346.
- Tanner, M.A. & Wong, W.H. (1987) The calculation of posterior distributions by data augmentation. *Journal of the American statistical Association*, **82**, 528–540.
- Zippin, C. (1958) The removal method of population estimation. *The Journal of Wildlife Management*, **22**, 82–90.